

# Digital surfaces in DGtal Topology module (since 0.5)

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D G t a l

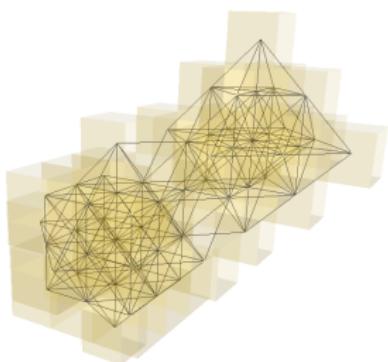


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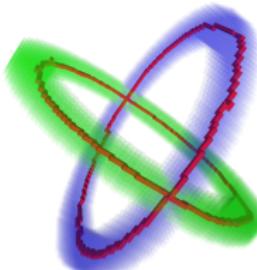
# Package Topology, available in DGtal 0.4

## 1. classical digital topology (*à la Rosenfeld*)

- ▶ Arbitrary adjacencies in  $\mathbb{Z}^n$ , but also in subdomains
- ▶ Digital topology = couple of adjacencies (Rosenfeld)
- ▶ Object = Topology + Set
- ▶ Operations : neighborhoods, border, connectedness and connected components, decomposition into digital layers, simple points



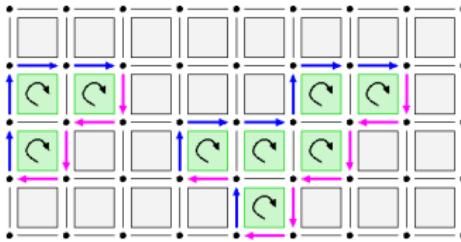
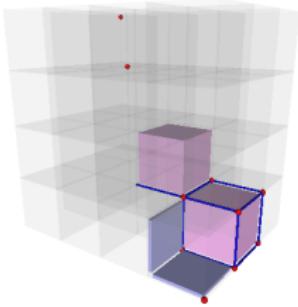
Adjacencies



thinning in (6,26)

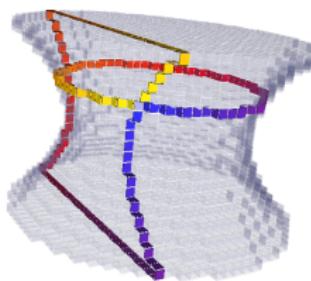
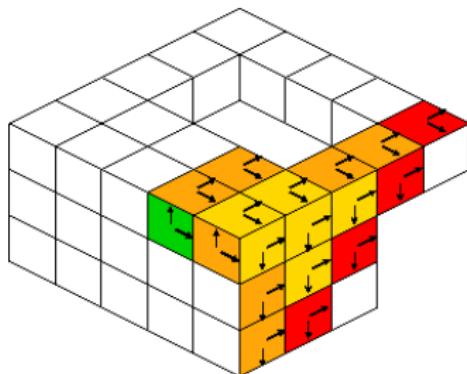
# Package Topology, available in DGtal 0.4

1. classical digital topology (*à la Rosenfeld*)
2. cubical cellular topology + algebraic topology
  - ▶ cells, adjacent and incident cells, faces and cofaces
  - ▶ signed cells, signed incidence, boundary operators



# Package Topology, available in DGtal 0.4

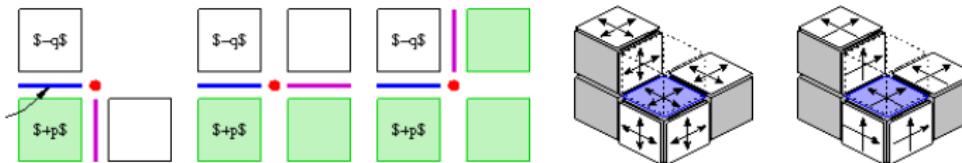
1. classical digital topology (*à la Rosenfeld*)
2. cubical cellular topology + algebraic topology
3. digital surface topology (*à la Herman*)
  - ▶ surfels, surfel adjacency, surfel neighborhood
  - ▶ surface tracking (normal, fast), contour tracking in  $n$ D



# Package Topology, new in DGtal 0.5

## Digital Surface

- surfels / signed  $n - 1$ -cells      }      • kind of "dual" graph  
+ adjacencies between surfels      }      • kind of manifold



# Package Topology, new in DGtal 0.5

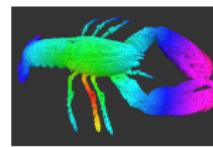
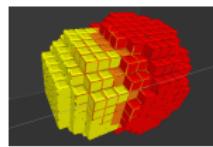
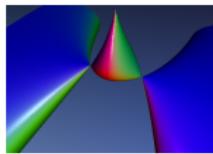
## Digital Surface

surfels / signed  $n - 1$ -cells      }      • kind of "dual" graph  
+ adjacencies between surfels      }      • kind of manifold

1. High-level `DigitalSurface` class for representing any kind of digital surface
2. Many container classes for digital surfaces
  - ▶ boundary of digital shape
  - ▶ boundary of implicitly defined shape
  - ▶ set of surfels
  - ▶ implicitly defined set of surfels
  - ▶ light containers
3. a `DigitalSurface` is a graph
4. a `DigitalSurface` is a combinatorial surface (with umbrellas)

# Direct applications

- marching cubes algorithm
- tracking implicit polynomial surfaces
- representing boundary of regions and frontier between regions
- breadth-first visiting on surfaces
- estimating normals on surfaces



# Necessary concepts and classes for digital surfaces

One must choose

- the representation of cellular grid space : model of  
**CCellularGridSpaceND**  
e.g. **KhalimskySpaceND< N, int >**, **Z2i::KSpace**, **Z3i::KSpace**
- the kind of adjacency between surfels, **SurfelAdjacency< N >**
- the kind of surface container : model of  
**CDigitalSurfaceContainer**

```
1  typedef Z3i::Point Point; // 3D digital point
2  typedef Z3i::Domain Domain;
3  typedef Z3i::DigitalSet DigitalSet; // a set of
        digital points
4  typedef Z3i::KSpace KSpace; // 3D cellular grid space
5  typedef SurfelAdjacency<3> SAdj; // surfel adjacency.
6  typedef DigitalSetBoundary<KSpace,DigitalSet>
        Container; // kind of surface container
7  typedef DigitalSurface<Container> MyDigSurf; //
        concrete digital surface
```

## Concrete instantiations for digital surfaces

Then, the chosen types are instantiated. Here  
digital surface = boundary of two intersecting balls

```
1   Point p1( -20, -20, -20 ), p2( 20, 20, 20 );
2   KSpace K; K.init( p1, p2, true ); // init space
3   DigitalSet someShape( Domain( p1, p2 ) );
4   Shapes<Domain>::addNorm2Ball( someShape, Point
      (-3,0,0), 4 );
5   Shapes<Domain>::addNorm2Ball( someShape, Point
      (3,0,0), 4 );
6   SAdj surfAdj( true ); // the adjacency
7   Container surfContainer( K, someShape, surfAdj );
8   MyDigSurf digSurf( surfContainer ); // digital
      surface
```

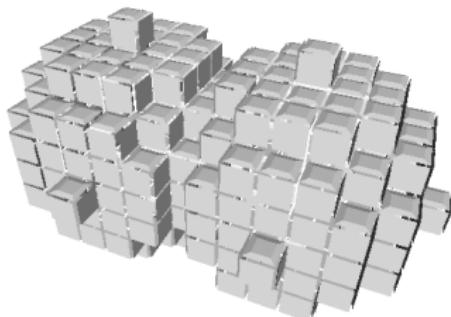
Using the digital surface (displays 518) :

```
1   cout << "-nb_surfels/vertices="
2           << digSurf.size() << endl;
```

# How to use digital surfaces (I)

Just enumerating its elements...

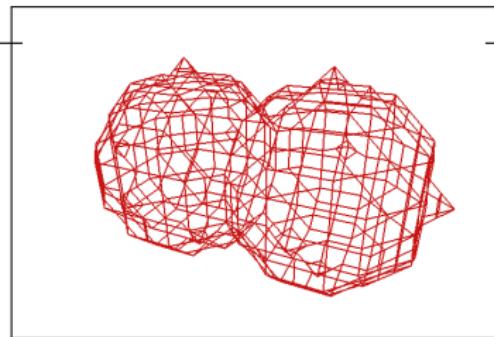
```
1  QApplication application( argc, argv );
2  Viewer3D viewer; // QGL viewer
3  viewer.show();
4  for( MyDigSurf::ConstIterator it = digSurf.begin(),
5      itend = digSurf.end(); it != itend; ++it )
6      viewer << *it;
7  viewer << Viewer3D::updateDisplay;
8  return application.exec();
```



# How to use digital surfaces (II)

Getting the neighbors and drawing the graph...

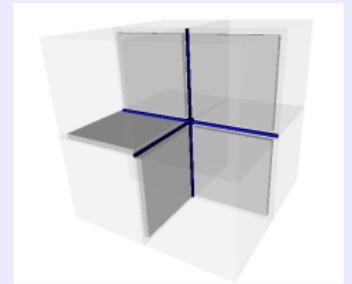
```
1  typedef std::vector<Vertex> Neighborhood;
2  for ( ConstIterator it = digSurf.begin(),
3        itend = digSurf.end(); it != itend; ++it )
4  {
5      Neighborhood N;
6      back_insert_iterator<Neighborhood> itN = back_inserter( N );
7      digSurf.writeNeighbors( itN , *it );
8      Point p = K.sKCoords( *it );
9      for ( unsigned int i = 0; i < N.size(); ++i )
10     {
11         Point q = K.sKCoords( N[ i ] );
12         viewer.addLine ( p[0]/2.0, p[1]/2.0, p[2]/2.0,
13                           q[0]/2.0, q[1]/2.0, q[2]/2.0,
14                           DGtal::Color ( 200,20,20 ), 2.0 );
15     }
16 }
```



# How to use digital surfaces (III)

Digital surfaces are combinatorial surfaces

- in  $n$ -D
- vertices =  $n - 1$ -cells
- edges  $\approx n - 2$ -cells
- faces  $\approx n - 3$ -cells



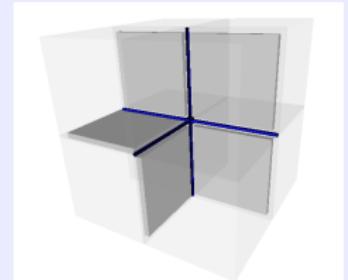
Inner types `Vertex`, `Arc`, `Face`, `xxxRange`, `xxxSet`

```
1 FaceRange    facesAroundVertex( const Vertex & v )
2 VertexRange  verticesAroundFace( const Face & f )
3 FaceRange    facesAroundArc( const Arc & a )
4 FaceSet      allFaces()
5 FaceSet      allClosedFaces()
6 FaceSet      allOpenFaces() ...
```

# How to use digital surfaces (III)

Digital surfaces are combinatorial surfaces

- in 3-D
- vertices = surfels
- edges  $\approx$  linels
- faces = umbrellas



Inner types `Vertex`, `Arc`, `Face`, `xxxRange`, `xxxSet`

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1 FaceRange    facesAroundVertex( const Vertex & v )
2 VertexRange  verticesAroundFace( const Face & f )
3 FaceRange    facesAroundArc( const Arc & a )
4 FaceSet      allFaces()
5 FaceSet      allClosedFaces()
6 FaceSet      allOpenFaces() ...
```

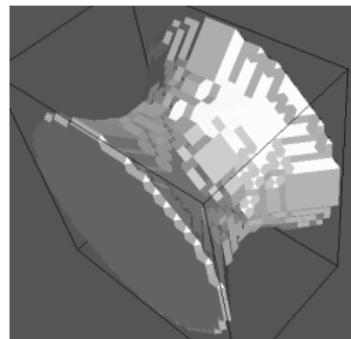
# How to use digital surfaces (IV)

## Getting the faces and outputting their vertices

```
1  typedef typename FaceSet::const_iterator FaceSetIter;
2  typedef typename VertexRange::const_iterator VertexRangeIter;
3  FaceSet faces = digSurf.allClosedFaces();
4  for ( FaceSetIter itf = faces.begin(),
5        itf_end = faces.end(); itf != itf_end; ++itf )
6  {
7      Face face = *itf;
8      out << face.nbVertices;
9      VertexRange vtcs = digSurf.verticesAroundFace( face );
10     for ( VertexRangeIter itv = vtcs.begin(),
11           itv_end = vtcs.end(); itv != itv_end; ++itv )
12         out << " " << index[ *itv ];
13     out << std::endl;
14 }
```

e.g. export in OFF format

```
1  void exportSurfaceAs3DOFF ( std::ostream
   & out )
2
3  template <typename CellEmbedder>
4  void exportEmbeddedSurfaceAs3DOFF
5  ( std::ostream & out, const CellEmbedder
   & cembedder )
```

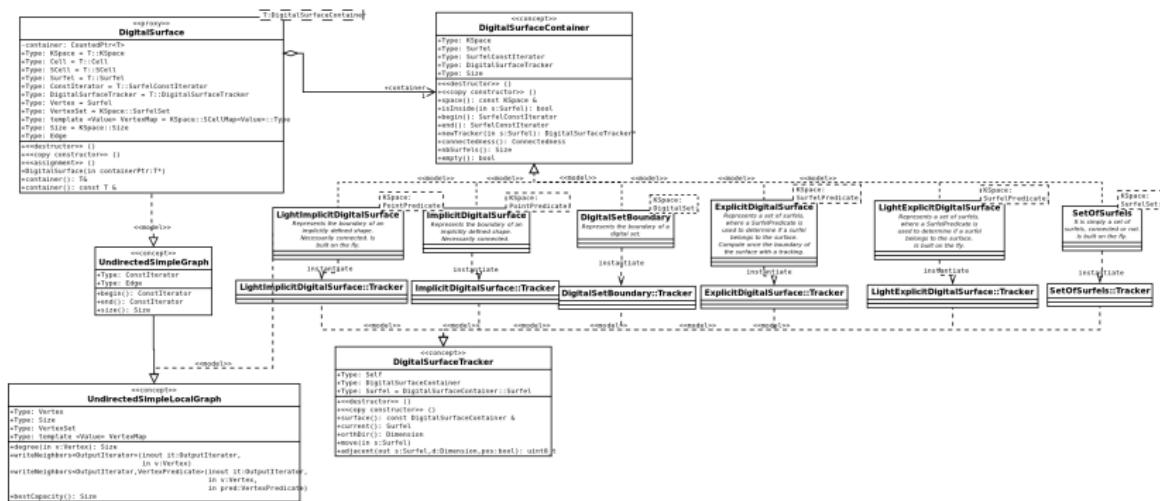


# Diversity of digital surfaces

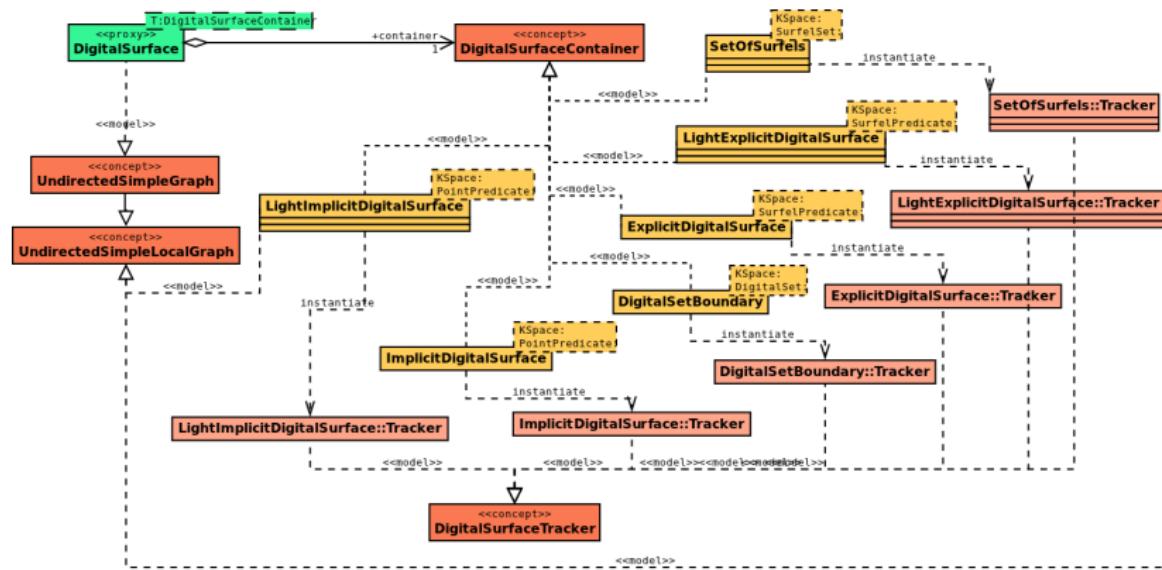
- may be open or closed
- may be connected or not
- may be defined explicitly with their surfels
- may be defined implicitly as the boundary of some shape
- the surfels may be listed or known only through a predicate
- the shape may be described by its points or known only through a predicate
- the surface may be big or infinite so that only lazy extraction is reasonable

You wish to process them with the same object : `DigitalSurface<T>`  
 $T$  is a model of `CDigitalSurfaceContainer`

## Partial architecture



# Partial architecture



## Digital surface containers

- `DigitalSetBoundary<KSpace, DigitalSet>` Represents the boundary of a digital set (a set of digital points, considered as the set of pixels/voxels/spels of the space).

⇒ interpixel boundary of a digital shape

## Digital surface containers

- `DigitalSetBoundary<KSpace, DigitalSet>` Represents the boundary of a digital set (a set of digital points, considered as the set of pixels/voxels/spels of the space).  
⇒ interpixel boundary of a digital shape
- `ImplicitDigitalSurface<KSpace, PointPredicate>` Represents the (connected) boundary of shape defined implicitly by a predicate. + `Light` version.  
⇒ implicit surface computed once or on-the-fly

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- `SetOfSurfels`<`KSpace`,`SurfelSet`> Represents an arbitrary set of surfels stored explicitly.  
⇒ arbitrary known surface : add topology to a set

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- `ExplicitDigitalSurface<KSpace, SurfelPredicate>` Represents a (connected) set of surfels defined implicitly by a predicate. + `Light` version.  
⇒ frontier between regions in images, computed once or on-the-fly

# Example : frontiers between regions in image (I)

Creating the labelled image...

```
1  using namespace Z3i;
2  typedef ImageContainerBySTLVector<Domain,DGtal::
3      uint8_t> Image;
4  Domain domain0( Point( 0,0,0 ), Point( 10, 10, 10 ) );
5  Domain domain1( Point( 2,2,2 ), Point( 8, 8, 8 ) );
6  Domain domain2( Point( 2,4,4 ), Point( 8, 6, 6 ) );
7  Image image( domain0 );
8  fill( image, domain0, 0 ); // label 0
9  fill( image, domain1, 1 ); // label 1
10 fill( image, domain2, 2 ); // label 2
11 KSpace K; // creating cellular space
12 K.init( domain0.lowerBound(), domain0.upperBound(),
13         true );
```

## Example : frontiers between regions in image (II)

Creating the frontier between region 1 and region 0...

```
1  typedef SurfelAdjacency<KSpace::dimension> SurfAdj;
2  typedef FrontierPredicate<KSpace, Image> FSurfPred;
3  typedef ExplicitDigitalSurface<KSpace,FSurfPred>
4      FrontierContainer;
5  typedef DigitalSurface<FrontierContainer> Frontier;
6  SurfAdj surfAdj( true ); // interior in all
7      directions.
8  // frontier between label 1 and 0 (connected part
9      with bel10)
10 SCell vox1 = K.sSpel( Point( 2,2,2 ), K.POS );
11 SCell bel10 = K.sIncident( vox1, 0, false );
12 FSurfPred surfPred10( K, image, 1, 0 );
13 Frontier frontier10 = // acquired
14     new FrontierContainer( K, surfPred10, surfAdj,
15         bel10 );
```

## Example : frontiers between regions in image (III)

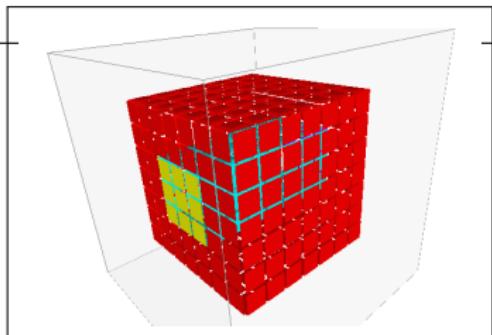
Idem for region 2 and 0 (two parts) and 2 and 1...

```
1 // frontier between label 2 and 0 (with bel20)
2 SCell vox2 = K.sSpel( Point( 2,4,4 ), K.POS );
3 SCell bel20 = K.sIncident( vox2, 0, false );
4 FFSurfPred surfPred20( K, image, 2, 0 );
5 Frontier frontier20 =
6     new FrontierContainer( K, surfPred20, surfAdj, bel20 );
7 // frontier between label 2 and 0 (with bel20bis)
8 SCell vox2bis = K.sSpel( Point( 8,6,6 ), K.POS );
9 SCell bel20bis = K.sIncident( vox2bis, 0, true );
10 FFSurfPred surfPred20bis( K, image, 2, 0 );
11 Frontier frontier20bis =
12     new FrontierContainer( K, surfPred20bis, surfAdj, bel20bis );
13 trace.endBlock();
14 // frontier between label 2 and 1 (with bel21)
15 SCell bel21 = K.sIncident( vox2, 1, false );
16 FFSurfPred surfPred21( K, image, 2, 1 );
17 Frontier frontier21 =
18     new FrontierContainer( K, surfPred21, surfAdj, bel21 );
```

# Example : frontiers between regions in image (III)

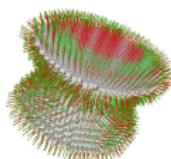
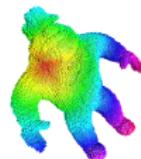
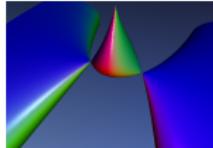
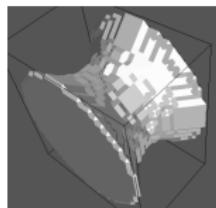
## Displaying surfaces...

```
1  QApplication application(argc,argv);
2  Viewer3D viewer;
3  viewer.show();
4  viewer << SetMode3D( domain0.className(), "BoundingBox" )
5      << domain0;
6  Cell dummy;
7  // Display frontier between 1 and 0 in RED
8  unsigned int nbSurfels10 = 0;
9  viewer << CustomColors3D( Color::Red, Color::Red );
10 for ( Frontier::ConstIterator
11     it = frontier10.begin(), it_end = frontier10.end();
12     it != it_end; ++it, ++nbSurfels10 )
13     viewer << *it;
14 // Display frontier between 2 and 0 in MAGENTA and YELLOW
15 // Display frontier between 2 and 1 in CYAN
16 ...
```



# More fun... current simple applications

```
1 cd examples/topology
2 # marching cubes algorithm
3 ./volMarchingCubes cat10.vol 1 255 0
4 geomview marching-cube.off
5 # tracking implicit polynomial surfaces
6 ./trackImplicitPolynomialSurfaceToOFF "3*x^2-2*y^2+z^3+5y^2*(z-1)*(z+1)
    " -2 -2 -2 2 2 2 0.05
7 geomview marching-cube.off
8 # breadth-first visiting on surfaces
9 ./volBreadthFirstTraversal Al.100.vol 0 255
10 # More elaborate example: estimating normals on surfaces
11 cd ../../tests/geometry/surfaces
12 ./testLocalConvolutionNormalVectorEstimator
```



## Next objectives (from 0.4 to 0.5)

### 1. classical digital topology

- ▶ other adjacencies (**no**)
- ▶ Adjacency = unoriented graph, associated concepts (**part**)
- ▶ make everything faster with specialization (especially simpleness) (**part**)

### 2. cubical cellular topology

- ▶ cellular grid space concept (**yes**)
- ▶ cubical complexes, interior, closure (**no**)
- ▶ path, mapping (homotopy) (**no**)
- ▶ chains, boundary operator, cochains, coboundary (**no**)
- ▶ (co)homology (**no**)

### 3. digital surface topology

- ▶ digital surface concept (**yes**)
- ▶ digital surface graph and cograph (umbrellas) (**yes**)
- ▶ digital surface map (**part**)

# Topology package description (as of 0.5)

## Content

- classical digital topology à la Rosenfeld
- cartesian cellular topology
- digital surface topology à la Herman
- base block of geometric algorithms

## Examples

- adjacencies, connected components, simple points, thinning
- cells, boundary operators, incidence, opening, closing
- contours, surfel adjacency, surface tracking
- high-level manipulation of digital surfaces

## Location

- {DGtal}/src/DGtal/topology
- {DGtal}/src/DGtal/helpers
- {DGtal}/tests/topology
- {DGtal}/examples/topology