

Image restoration and segmentation using the Ambrosio-Tortorelli functional and discrete calculus

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ICPR 2016, Cancun, Mexico

6 December 2016

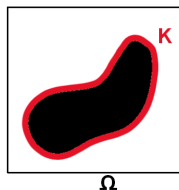
Mumford-Shah functional

[Mumford and Shah, 1989]

We minimize :

$$\mathcal{MS}(K, u) = \underbrace{\int_{\Omega \setminus K} |u - g|^2 \, dx}_{\text{fidelity term}} + \alpha \underbrace{\int_{\Omega \setminus K} |\nabla u|^2 \, dx}_{\text{smoothness term}} + \lambda \underbrace{\mathcal{H}^1(K \cap \Omega)}_{\text{discontinuities length}}$$

- Ω the image domain
- g the input image
- u a piecewise smooth approximation of g
- K the discontinuities set
- \mathcal{H}^1 the Hausdorff measure



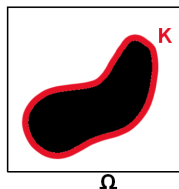
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Ambrosio-Tortorelli functional

[Ambrosio and Tortorelli, 1992]

$$AT_{\varepsilon}(u, v) = \alpha \int_{\Omega} |u - g|^2 \, dx + \int_{\Omega} v^2 |\nabla u|^2 \, dx + \lambda \int_{\Omega} \varepsilon |\nabla v|^2 + \frac{1}{\varepsilon} \frac{(1 - v)^2}{4} \, dx$$

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- v a smooth approximation of $1 - \chi_K$

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- ✓ whole domain integration
- ✓ no Hausdorff measure

Ambrosio-Tortorelli functional

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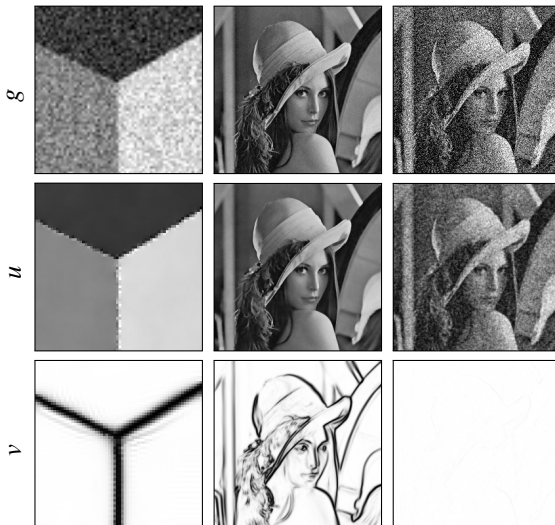
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$$AT_{\varepsilon}(u, v) \xrightarrow{\Gamma} \mathcal{MS}$$



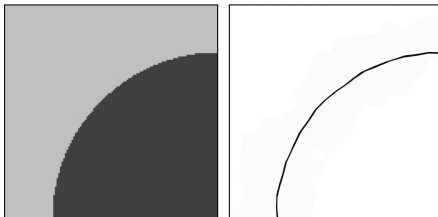
Finite differences implementation





Finite elements implementation

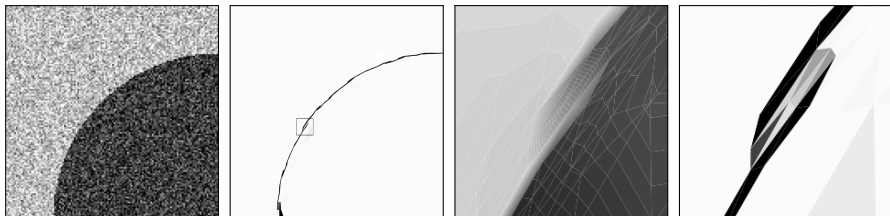
- ▷ Proposed in [Bourdin and Chambolle, 2000]





Finite elements implementation

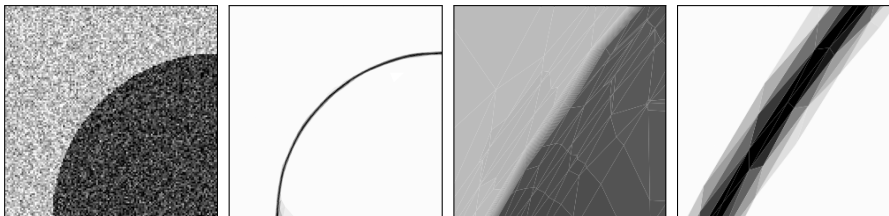
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Finite elements implementation

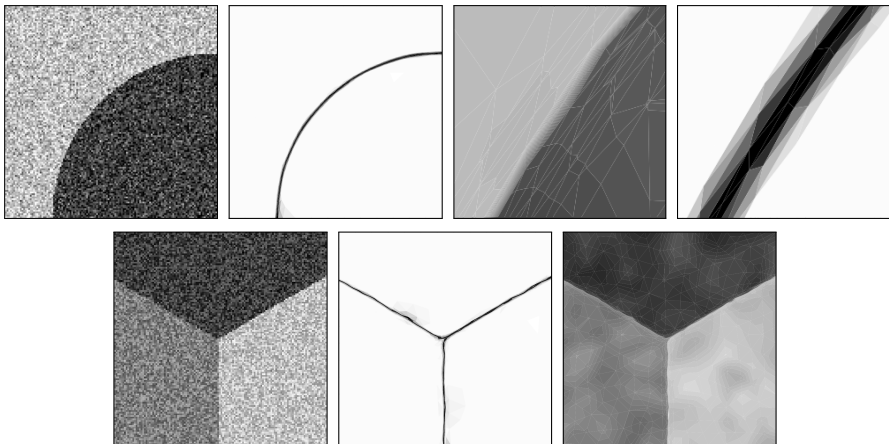
- ▷ Proposed in [Bourdin and Chambolle, 2000]
- ▷ Finite elements with mesh **refinement** and **realignment**





Finite elements implementation

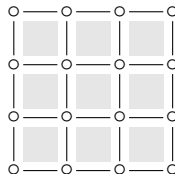
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Discrete Calculus

Cell complex

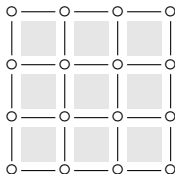
- We decompose the image domain into a cell complex
 - ▷ faces : pixels
 - ▷ edges : sides shared by 2 pixels
 - ▷ vertices : vertices shared by 4 pixels



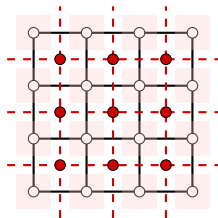
Discrete Calculus

Cell complex

- We decompose the image domain into a cell complex
 - ▷ faces : pixels
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- Dual complex :
 - ▷ dual vertices : centers of primal faces
 - ▷ dual edges : edges orthogonal to primal edges
 - ▷ dual faces : delineated by dual vertices and edges



primal

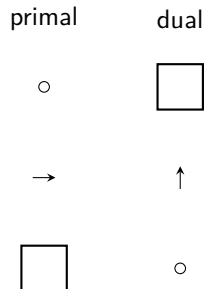


dual

Discrete Calculus

Discrete operators

- **Discrete k -form** associates a scalar to a k -dimensional cell (represented by column vectors)

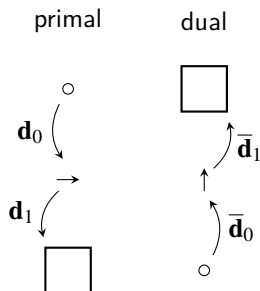


[Grady and Polimeni, 2010]

Discrete Calculus

Discrete operators

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- **Derivative operators \mathbf{d}_k** are the oriented k -cells to $(k+1)$ -cells incidence matrix

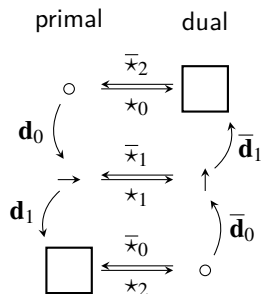


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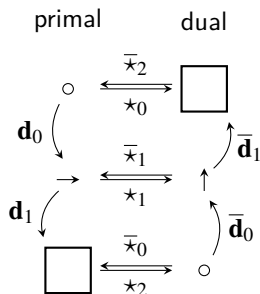


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- $\mathbf{M}_{01} = \frac{1}{2}|\mathbf{d}_0|$ transforms a 0-form into a 1-form by averaging the values on the two edge extremities
- **"Edge Laplacian"** : $\bar{\star}_1 \bar{\mathbf{d}}_0 \star_2 \mathbf{d}_1 + \mathbf{d}_0 \bar{\star}_2 \bar{\mathbf{d}}_1 \star_1$

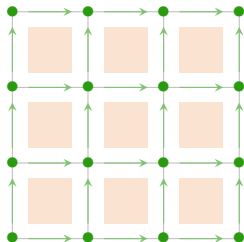


[Grady and Polimeni, 2010]



Discrete formulation of AT

On faces and vertices

$$AT_{\varepsilon}(u, v) = \alpha \int_{\Omega} |u - g|^2 \, dx + \int_{\Omega} v^2 |\nabla u|^2 \, dx + \lambda \int_{\Omega} \varepsilon |\nabla v|^2 + \frac{1}{\varepsilon} \frac{(1 - v)^2}{4} \, dx$$



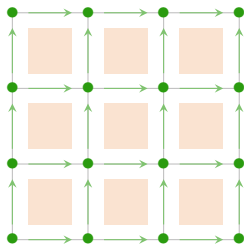
We choose :

- u, g to live on faces 
 - ▷ u, g are 2-forms
- v to live on vertices 
 - ▷ v is a 0-form

Discrete formulation of AT

On faces and vertices

$$AT_{\varepsilon}(u, v) = \alpha \int_{\Omega} |u - g|^2 \, dx + \int_{\Omega} v^2 |\nabla_2 u|^2 \, dx + \lambda \int_{\Omega} \varepsilon |\nabla_0 v|^2 + \frac{1}{\varepsilon} \frac{(1 - v)^2}{4} \, dx$$



We choose :

- u, g to live on faces 

▷ u, g are 2-forms

- v to live on vertices ●

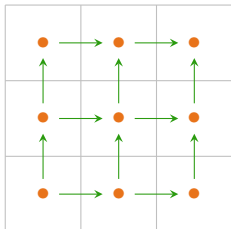
▷ v is a 0-form

$$AT_{\varepsilon}^{2,0}(u, v) = \alpha \langle u - g, u - g \rangle_2 + \langle \mathbf{M}_{01} v \wedge \bar{\star}_1 \bar{\mathbf{d}}_0 \star_2 u, \mathbf{M}_{01} v \wedge \bar{\star}_1 \bar{\mathbf{d}}_0 \star_2 u \rangle_1 \\ + \lambda \varepsilon \langle \mathbf{d}_0 v, \mathbf{d}_0 v \rangle_1 + \frac{\lambda}{4\varepsilon} \langle 1 - v, 1 - v \rangle_0$$

Discrete formulation of AT

On vertices and edges

$$AT_{\varepsilon}(u, v) = \alpha \int_{\Omega} |u - g|^2 \, dx + \int_{\Omega} v^2 |\nabla u|^2 \, dx + \lambda \int_{\Omega} \varepsilon |\nabla v|^2 + \frac{1}{\varepsilon} \frac{(1 - v)^2}{4} \, dx$$



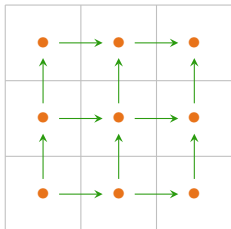
We choose :

- u, g to live on vertices ●
 - ▷ u, g are **0-forms**
- v to live on edges →
 - ▷ v is a **1-form**

Discrete formulation of AT

On vertices and edges

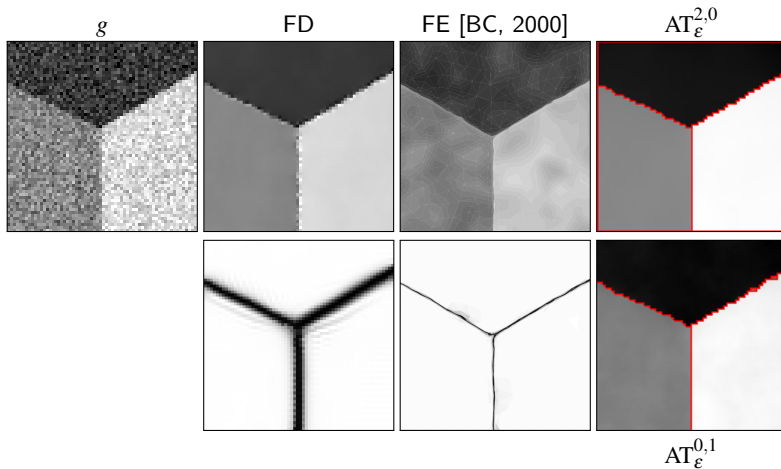
$$AT_\varepsilon(u, v) = \alpha \int_\Omega |u - g|^2 \, dx + \int_\Omega v^2 |\nabla_0 u|^2 \, dx + \lambda \int_\Omega \varepsilon |\nabla_1 v|^2 + \frac{1}{\varepsilon} \frac{(1 - v)^2}{4} \, dx$$

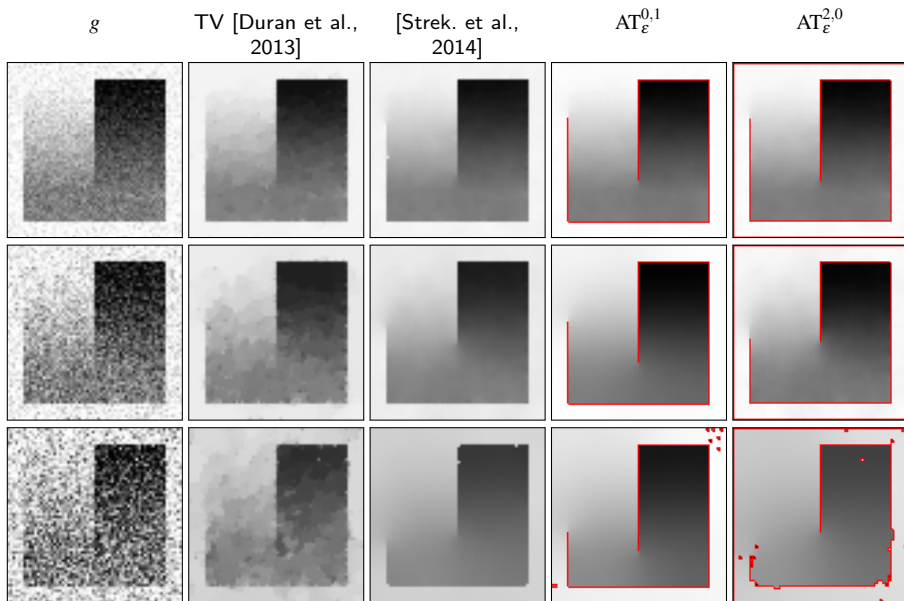


We choose :

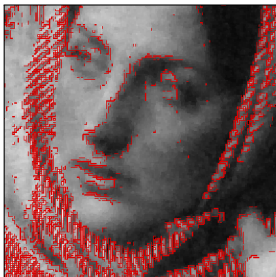
- u, g to live on vertices ●
 - ▷ u, g are **0-forms**
- v to live on edges →
 - ▷ v is a **1-form**

$$AT_\varepsilon^{0,1}(u, v) = \alpha \langle u - g, u - g \rangle_0 + \langle v \wedge \mathbf{d}_0 u, v \wedge \mathbf{d}_0 u \rangle_1 + \lambda \varepsilon \langle (\mathbf{d}_1 + \bar{\star}_2 \bar{\mathbf{d}}_1 \star_1) v, (\mathbf{d}_1 + \bar{\star}_2 \bar{\mathbf{d}}_1 \star_1) v \rangle_2 + \frac{\lambda}{4\varepsilon} \langle 1 - v, 1 - v \rangle_1$$





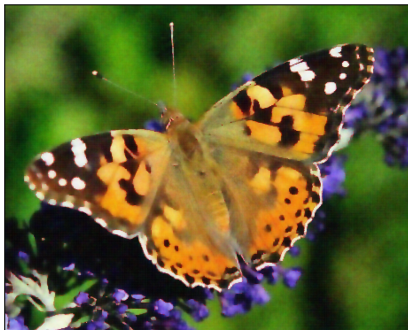
Numerical results

 g (PSNR = 26.1 dB) u (PSNR = 29.9 dB) $AT_{\varepsilon}^{2,0}$  $AT_{\varepsilon}^{0,1}$





g (PSNR = 20.83 dB)



u (PSNR = 27.29 dB)

Conclusion

- **Standard discretization schemes**, such as finite differences or finite elements, lead to numerical difficulties
- **Discrete calculus** enables to reconstruct **1D contours** and smooth regions

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Perspectives

- Add **anisotropy**
- Work on **non-image data**
- **Other applications** : deblurring, tomography, 3D surface reconstruction, ...



Digital Geometry Tools and Algorithms - <http://dgtal.org>

Références I



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